K.S.R.M. College of Engineering - KADAPA

(AUTONOMOUS)

Department of Electrical & Electronics Engineering

B. Tech – V Semester (Theory - 5, Lab - 3)

S. No.	Subject Code	SUBJECT	SC	L	Т	Р	IM	EM	CR
1	1814501	Microprocessor	PCC	3	0	0	30	70	3
2	1814502	Linear Digital IC Applications	PCC	3	0	0	30	70	3
3	1802503	Power Electronics	PCC	3	0	0	30	70	3
4	1802504	Power System Operation & Control	PCC	3	1	0	30	70	4
		Professional Elective-I (PE-I)							
_	1802505	Energy Auditing & Demand Side Management	PEC	3	0	0	30	70	3
5	1802506	Electrical Machine Design	PEC	3	0	0	30	70	3
	1802507	Advanced Control Systems	PEC	3	0	0	30	70	3
	1802508	Instrumentation	PEC	3	0	0	30	70	3
	1802509	Energy Conversion Systems	PEC	3	0	0	30	70	3
6	1802510	Electrical Machines - II Lab	PCC	0	0	3	50	50	1.5
7	1802511	Control Systems & Simulation Lab	PCC	0	0	3	50	50	1.5
8	1824512	Advanced English Communication Lab	HS MC	0	0	2	50	50	1
10	1802513	Mini Project (60 hrs/Semester)	PROJ	-	-	-	100	-	2
		Total		15	01	08	400	500	22

B.Tech., V Semester

Course	Title	Microproces	sors &	Microco	ontrolle	rs	B. Tech. EC	E V Sem			
Course	Code	Category	Ho	ours/We	ek	Credits	Maxin	num Mar	ks		
1804506		EC	L	Т	Р	С	Continuous Internal Assessment	End Exams	Total		
			3			3	30	70	100		
Mid Exa	m Duration: 1Hr 30 Min End Exam Duration: 3Hrs										
Course (Objecti	ives:									
• T	o becon	me familiar with	h 8086 N	Micropro	ocessor a	and 8051 N	Microcontroller	r Architec	ture,		
Iı	nstructi	ons, Operating	Modes a	und Prog	rammin	g.					
• T	o use 8	086 microproce	essor and	d 8051 n	nicrocor	ntroller for	various applic	ations.			
• T	o study	various periph	erals for	^r microp	rocesso	r based sy	stems.				
Course (Outcon	nes: On success	ful com	pletion of	of this c	ourse, the	students will be	e able to			
CO 1	Defin	e various comp	onents a	nd list o	ut vario	us features	s of microproce	essor,			
	micro	controller and p	eriphera	ls.							
CO 2	Descr	ibe the internal	block di	iagram c	of micro	processor,	microcontrolle	er and per	ipherals,		
	addres	sing modes, ins	truction	set and	data tra	nsfer schei	mes.				
CO 3	Devel	op algorithm ar	nd assem	nbly lang	guage pi	ograms to	solve problem	IS.			
CO 4	Apply	an appropriate	algorith	nm, prog	gram and	l periphera	l for the applic	ation.			
CO 5	Design	n the microproc	essor or	microco	ontroller	based sys	tem to solve re	al time pr	oblems.		
	(Prepa	re a case study	model to	o get a fi	irst prot	otype)					

UNIT I

Introduction to Microprocessors: 8085 Microprocessor - Architecture, Instruction set, Addressing modes, Basic Timing Diagrams, Interrupts and Simple Programs.

8086 Microprocessor - Architecture, Instruction set, Addressing modes, Interrupt system. Pin diagram, Minimum mode 8086 system and timings, Maximum mode 8086 system and timings.

UNIT II

Assembly Language Programming: Assembler directives, Assembly language programs (8086) with Assembler directives for addition, subtraction, multiplication, division etc., sorting and searching, bit manipulation, look-up tables, string manipulations, Macros and Delay subroutines.

Data transfer schemes and Memory Interfacing: Synchronous, Asynchronous, Interrupt driven and DMA type schemes, Address decoding techniques, Interfacing Static RAM and ROM chips,

UNIT III

Peripheral Interfacing: 8255 PPI and its interfacing, Programmable Communication Interface (8251 USART) and its interfacing, Programmable Interval Timer (8254) and its

interfacing, Programmable interrupt controller (8259) and its interfacing, Programmable DMA controller (8257) and its interfacing, ADC and DAC Interfacing.

UNIT IV

The 8051 microcontroller: Architecture, pin diagram, memory organization, external memory interfacing, stack, addressing modes, instruction set, Assembler directives, Assembly Language programs and Time delay Calculations, 8051 interrupt structure, 8051 counters and Timers, programming 8051 timers.

UNIT V

Introduction to ARM: ARM Design philosophy, Registers, Program Status Register, Instruction pipeline, Interrupts and vector table, Instruction Set- Data Processing Instructions, Branch, Load-Store, Software interrupt, PSR instructions, Conditional instructions, Thumb instruction Set: Register Usage, Other Branch instructions, Data processing Instructions, Single-Register and Multi Register Load-Store Instructions, Stack, Software Interrupt Instructions.

Text Books:

- 1. Ramesh S. Gaonkar, "Microprocessor architecture, programming and its applications with 8085", Penram International Publications, 4th Edition.
- 2. A. K. Ray and K.M. Bhurchandi, "Advanced Microprocessors and Peripherals", TMH.
- 3. The 8051Microcontroller and Embedded Systems, Mazidi Muhammad Ali, Mazidi Janice Gillespie & McKinlay Rolin D, 2nd Edition, Pearson Education, 2008.
- 4. The 8051 microcontroller: Architecture, Programming & Applications, Kenneth J Ayala, penram publications, 2nd edition.
- 5. ARM System Developer's Guide-Designing and Optimizing system software, Andrew N.Sloss, Dominic Symes, Chris Wright, Elsevier, 2008.

Reference Books:

- 1. Douglas V. Hall, "Microprocessors and Interfacing: Programming and Hardware", 2nd Edition, Tata McGraw-Hill.
- 2. Barry B. Brey, "The Intel Microprocessors-Architecture, Programming and Interfacing", 8th Edition, PHI.
- 3. Y. Liu and Glenn A. Gibson, "Microcomputer Systems: 8086/8088 Family Architecture, Programming and Design", 2nd Edition, PHI.
- 4. Microcontrollers Architecture, Programming, Interfacing and System Design Raj Kamal, Pearson Education, 2005.
- 5. Steve Furbur, ARM System onchip Architecture, 2nd Edition, Addison Wesley, 2000.

Linear and Digital IC Applications

Course Objectives:

- To give introduction to Op-Amps
- To study about Timers and PLLs
- To Learn the applications of Op-Amps.
- To introduce **Verilog** and its language elements to design digital systems.
- Make students familiar with design of different combinational and sequential digital circuits.

Learning Outcomes:

CO1: Understand the operation and characteristics of OP-AMPs.
CO2: Analyze multivibrator circuits and 555 timers using OP-AMPs.
CO3: Apply PLL in various Communication applications
CO4: Compare various digital logic families.
CO5: Simulate digital logic circuits using Verilog HDL.

UNIT-I

OP-AMP AND ITS CHARACTERISTICS

Integrated circuits -types, classification, package types and temperature ranges, power supplies, OP-Amp Block diagram, ideal and practical OP-Amp specifications, DC and AC characteristics, 741 OP-Amp and its features, Inverting and non-inverting amplifier.

UNIT-II

OP-AMP APPLICATIONS

Integrator and differentiator, difference amplifier, instrumentation amplifier, AC amplifier, V-I, I-V converters, comparators, Multivibrators, Triangular and square wave generators, Log and antilog amplifiers, precision rectifiers.

UNIT-III

TIMERS AND PHASE LOCKED LOOPS

Introduction to 555 Timer, functional diagram, Monostable and Astable operations, Schmitt Trigger, PLL-Introduction, Block schematic, principles and description of individual blocks, 565 PLL, applications.

UNIT-IV

UNIPOLAR & BIPOLAR LOGIC FAMILIES

Introduction to logic families, CMOS logic, CMOS steady state electrical behavior, CMOS dynamic state electrical behavior, CMOS logic families, Bipolar logic, transistor logic, TTL families, CMOS/TTL interfacing, ECL, Comparison of logic families.

UNIT-V

VERILOG HDL AND DESIGN EXAMPLES

HDL based Design flow, Program Structure, Logic system, Nets, Variables and Constants, Vectors and Operators, Arrays, Logical Operators and Expressions. Structural design elements, data flow design elements, behavioral design elements (procedural code). Design using basic gates, Decoders, Encoders, Multiplexers and Demultiplexers, Adders, Subtractors, SSI Latches and Flip-Flops, Counters, Design of Counters and Shift Registers .**Verilog** Modules for the above ICs.

Text Books:

1. Ramakanth A. Gayakwad, "Op-Amps & Linear ICs", 4th edition, PHI, 1987.

- 2. John F. Wakerly, "Digital Design Principles & Practices" PHI/Pearson Education Asia, 4th Edition, 2008.
- 3. J. Bhasker, "A Verilog HDL Primer", Star Galaxy Publishing; 3rd edition (January 31, 2005)

References:

- 1. D. Roy Chowdhury, "Linear Integrated Circuits", New Age International (P) Ltd, 2nd Edition, 2003.
- 2. James M.Fiore, "Operational Amplifiers & Linear integrated circuits & applications", Cengage 2009.
- 3. Fundamentals of Digital Logic with Verilog Design Stephen Brown, Zvonko Vranesic, TMH, 3rd Edition, 2014

Course Title	Powe	r Ele	ctron	ics		B. Tech. V Sem					
Course Code	Category	Но	urs/Week Credits		Credits	Maximum	um Marks End Total				
1802503	Professional L T P C Core (PCC)		С	Continuous Internal Assessment	Total						
	(PCC)	3	0	0	3	30 70 100					
	Mid Exam Dura	tion :	2Hrs	3		End Exam Duration : 3Hrs					
Course Obj devices, conv	ectives: The object verters, choppers an	tive o d invo	of the erters	cour and t	rse is to le heir analys	earn the basic concepts of is.	power sen	niconductor			
Course Outo	comes: On successf	ul cor	npleti	on of	this course	e, the students will be able to	0				
CO 1	Understand the ba	isic op	peratio	on of	power sem	iconductor devices and pass	sive compor	ients.			
CO 2	Analyze the perfo	rmano	ce of o	liffer	ent power c	converters subjected to vario	ous loads.				
CO 3	Design static and	dynar	nic eq	lualiz	ing circuits	, Snubber circuits.					
CO 4	Evaluate number and different varia	of SC	Rs re: CRs re	quire ious p	d for desire	ed series /parallel operation ronic circuits.	ı, Electrical	parameters			
CO 5											

<u>UNIT - I</u>

Silicon Controlled Rectifier: SCR – static characteristics –turn on and off mechanism – gate characteristics – dynamic characteristics – series and parallel operation of scr's – static and dynamic equalization circuits – design of snubber circuit – line commutation and forced commutation circuits, MOSFET, IGBT, GTO Characteristics.

<u>UNIT - II</u>

Phase controlled Rectifiers: Phase controlled rectifiers – single phase half and fully controlled converters – midpoint and bridge connections with R and RL loads – effect of source inductance- single phase and three phase half and fully controlled converters with R load - single phase and three phase dual converters with R and RL loads-numerical problems.

<u>UNIT - III</u>

AC Voltage Controllers: AC voltage controllers- single phase ac voltage controllers with SCR and triac for R and RL load –cyclo converters – single phase cyclo converters (midpoint and bridge configuration) with R and RL loads.

UNIT - IV

Choppers: Choppers – principle of operation – control strategies- types of chopper circuits – type A, type B, type C, type D and type E chopper circuits – multiphase chopper circuits – buck converter, boost converter, buck -boost converter, problems.

UNIT - V

Inverters: Inverters – single phase inverter – basic series inverter – basic parallel capacitor inverter – bridge inverter – current source inverter - forced commutation circuits for bridge inverters – output voltage control techniques- PWM techniques- space vector modulation - harmonic reduction techniques.

Text Books

- 1. Power Electronics By M.D Singh & K.B. Kanchandhani, Tata McGrawHill Publishing Company, 1998.
- 2. Power Electronics Circuits, Devices and Applications by M.H. Rashid, Prentice Hall of India, 2nd Edition 1998.
- 3. Power Electronics- by PS Bimbhra, Khanna Publications.

Reference Books

- 1. Power Electronics By Vedam Subramanyam, New Age Information Limited, 3rd Edition.
- 2. Power Electronics By V.R. Murthy, Oxford University Press, 1st Edition 2005
- 3. Power Electronics By P.C Sen, Tata Mc Graw Hill Publishing.
- 4. Thyristorised Power Controllers By G.K. Dubey, S. R. Doradla, A. Joshi and R. M. K. Sinha, New Age Informational(p) Limited Publishing 1996.

Course Title	Power System	Oper	ation	& C	ontrol	B. Tech. V Sem					
Course Code	Category	Ηοι	ırs/W	eek	Credits	Maximum Marks					
1802504	Professional Core (PCC)	L	Т	Р	С	Continuous Internal Assessment	End Exam	Total			
	(FCC)	3	0	0	3	30	70	100			
	Mid Exam Durat	ion : 1	2Hrs			End Exam Durati	ion : 3Hrs				
Course Object economic opecarea and two	ectives: The objection of power sy area load frequency	ive of stems contr	the , hyd ol.	cours lrothe	e is to lea ermal scheo	rn steady state and transien duling, modeling of governo	t stability a r, generator,	nalysis, , single			
Course Outc	omes: On successfu	ıl com	pletio	on of	this course	, the students will be able to					
CO 1	Analyze the stabil	ity of	the p	ower	system un	ler different operating condi	tions				
CO 2	Understand optim power system com	al op	erationts fo	on of r LFC	thermal u C studies.	nit, hydrothermal scheduling	g and mode	ling of			
CO 3	Analyze economic operation criteria of thermal unit, hydrothermal units, modeling of turbine and governor.										
CO 4	Analyze load frequency control parameters in single and two area systems.										
CO 5	Design suitable co	ontroll	ers to	impi	rove LFC d	ynamics in single and two ar	ea power sys	stems.			

<u>UNIT I</u>

Stability Studies: Classification of stability studies – the power flow equations of wound rotor and salient pole synchronous machine connected to infinite bus through a transmission system – power angle diagrams – steady state stability and limits.

Transient Stability Analysis: General considerations and assumptions –inertia constant, derivation of swing equations, equal area criterion – application of equal area criterion to a) sudden increase in input b) sudden three phase fault on one of the lines of a transmission system – determination of critical clearing angle – clearing time- – limitations of equal area criterion, methods for improving power system stability.

<u>UNIT II</u>

Economic Operation: Optimal operation of thermal power units, - heat rate curve – cost curve–incremental fuel and production costs, input-output characteristics, optimum generation allocation with line losses neglected. Optimum generation allocation including the effect of transmission line losses – loss coefficients, general transmission line loss formula.

<u>UNIT III</u>

Hydrothermal Scheduling: optimal scheduling of hydrothermal system: hydroelectric power plant models, scheduling problems- short term hydrothermal scheduling problem.

Modeling of Turbine: First order turbine model, block diagram representation of steam turbines and approximate linear models.

Modeling of Governor: Mathematical modeling of speed governing system , derivation of small signal transfer function – block diagram.

UNIT IV

Load Frequency Control: Necessity of keeping frequency constant, definitions of control area, single area control, block diagram representation of an isolated power system, steady state analysis dynamic response, uncontrolled case.

<u>UNIT V</u>

Load Frequency Control-II: Load frequency control of two -area system – uncontrolled case and controlled case, tie-line bias control, proportional plus integral control of two area and its block diagram representation, steady state response, load frequency control and economic dispatch control.

Text Books

- 1. Electrical Power Systems by C.L. Wadhwa, New Age Internationa Publishers, 6th Edition,
- 2. Power System Analysis Operation and Control by A. Chakravarthy and S. Halder, 3rd Edition, PHI, 2012.
- 3. Modern Power System Analysis by I. J. Nagrath & D. P. Kothari, Tata Mc Graw Hill Publishing Company Ltd, 2nd Edition, 2003.
- 4. Power Systems Analysis and Stability by S.S.Vadhera, Khanna Publications.

Reference Books

- 1. Power System Analysis and Design by J. Duncan Glover and M.S. Sharma., THOMSON, 3rd Edition, 2008.
- 2. Electric Power Systems by S. A. Nasar, Schaum Outline Series, Revised 1st Edition, TMH, 2005.

Course Title	Energy Auditing & Dem (PE	nand - I)	Side	Mar	nagement	B. Tech. V Semester					
Course Code	Category	Ho We	urs / æk	Maximum Marks							
1802505	Professional Elective Core	L	Т	Р	С	Continuous Internal AssessmentEnd Exam					
	(PEC)	30	70	100							
	Mid Exam Duration		End Exam Duration : 3Hrs								
Course Obj schemes, dif management	ectives: The objective of ferent methods to improve	the c pow	ourse er fac	e is t ctor,	o learn abo lighting an	out energy auditing practi- d energy instruments, load	ces, conse l and demai	rvation nd side			
Course Out	comes: On successful comp	oletio	on of t	this c	ourse, the s	students will be able to					
CO 1	Understand energy audit management	ing p	practi	ces,	energy co	nservation schemes, energ	gy economi	cs and			
CO 2	Analyze energy conservation measures, energy auditing practices, energy economics and management										
CO 3	Design an appropriate ene	ergy c	conse	rvati	on scheme	for commercial and indust	rial applicat	tions			

CO 4 Choose appropriate technique for energy auditing and conservation.

<u>UNIT – I</u>

Energy Auditing: Energy audit- definitions, concept, types of audit, energy index, cost index, pie charts, sankey diagrams, load profiles, energy conservation schemes. measurements in energy audits, presentation of energy audit results.

<u>UNIT - II</u>

Energy Efficient Motors: Energy efficient motors, constructional details, loss distribution, factors affecting efficiency, characteristics - variable speed, variable duty cycle systems, rms hp- voltage variation-voltage unbalance- over motoring- motor energy audit.

<u>UNIT – III</u>

Power Factor Improvement: Power Factor – methods of improvement, location of capacitors, pf with non linear loads, effect of harmonics on pf, pf motor controllers.

UNIT – IV

Lighting and Energy Instruments: Good lighting system design and practice, lighting control ,lighting energy audit - energy instruments- watt meter, data loggers, thermocouples, pyrometers, lux meters, tongue testers ,application of PLC's.

UNIT – V

Demand Side Management: Introduction to DSM, concept of DSM, benefits of DSM, different techniques of DSM – time of day pricing, multi-utility power exchange model, time of day models for planning.

Load Management: Load priority technique, peak clipping, peak shifting, valley filling, strategic conservation, energy efficient equipment. management and organization of energy conservation awareness programs.

Text Books

- 1. Electrical Power distribution by A. S. Pabla, TMH, 5th edition, 2004.
- 2. Energy management by W.R. Murphy & G. Mckay Butter worth, Heinemann publications.
- 3. Energy management hand book by W. C. Turner, John Wiley and Sons.

References

- 1. Energy management by Paul o' Callaghan, Mc-graw Hill Book company-1st edition, 1998.
- Energy efficient electric motors by John. C. Andreas, Marcel Dekker Inc Ltd., 2nd Edition, 1995.
- 3. Energy management and good lighting practice: Fuel Efficiency- Booklet12 EEO.
- 4. Recent Advances in Control and Management of Energy Systems by D. P. Sen, K. R. Padiyar, Indrane Sen, M. A. Pai, Interline Publisher, Bangalore, 1993.
- 5. Energy Demand Analysis, Management and Conservation, Ashok V. Desai, Wiley Eastern, 2005.

Course Title	Electrical Ma	chine	Desig	gn (Pl	E – I)	B. Tech. V Semester						
Course Code	Category	Hou Wee	ırs / ek		Credits	Maximum	ım Marks l End Tot Exam					
1802506	Professional 506 Elective Core			Р	С	Continuous Internal Assessment	End Exam	Total				
	(PEC)	3	1	0	3	30 70 100						
	Mid Exam Durat	ion: 2	2Hrs			End Exam Duration : 3Hrs						
Course Object design consider and cooling of	ctives: The objective of erations of transforme f machines.	of the ers, ro	course tating	e is to macl	learn the de nines, three j	sign specifications of elect phase induction motors, sy	sign specifications of electrical machines, basic phase induction motors, synchronous machines					
Course Outco	omes: On successful c	omple	etion o	of this	course, the	students will be able to						
CO 1	Understand various	lesigr	n spec	ificati	ons of Elect	rical Machines.						
CO 2	Estimate the design synchronous machin	Estimate the design specifications of DC machines, Transformers, Induction machines and synchronous machines.										
CO 3	Analyze the choice b	oetwee	en var	ious p	parameters li	ke type of windings, no.po	les, no.of slo	ots etc				
CO 4	Analyze the heating	and c	ooling	g of el	ectrical mac	hines						

The Design problem: Basic considerations, design specifications, ISI specifications, design constraints, specification of transformers, rotating machines.

Design of transformers: Types of transformer – core construction, output equation, principle of design of core, windings, yoke main dimensions (H & W) for single phase: core type, shell type. 3-phase – core type transformers estimation of no load current of transformer.

UNIT II

General concepts of rotating machines: Output equation of dc machines, ac machines, separation of D & L, choice of specific loadings.

Design of D.C machines: Choice of no. of poles, selection of no. of armature slots, choice of winding, estimation of conductor cross section of armature, design of field systems: tentative design of field winding of dc machines.

UNIT III

Design of 3-phase induction motor: Separation of D & L, ranges of Ampere conductors and Bav.

Stator design – Selection of no of stator slots, turns per phase, design of conductor cross section.

Rotor design - Selection of no of rotor slots, principles of design of squirrel cage rotor, design of slip ring rotor.

UNIT IV

Design of synchronous machines: Separation of D & L, choice of Ampere conductors & Bav - Short Circuit Ratio (SCR) and its significance.

Armature design – choice of no. of stator (Armature) slots, turns/phase, conductor cross section for both salient pole and cylindrical pole machines.

<u>UNIT V</u>

Heating & Cooling of electrical machines: Theory of Solid body heating, heating time constant- cooling time constant, elementary treatment of cooling and heating time curves.

Cooling of machines: Volume of coolant required, types of coolants, cooling methods of transformer-hydrogen cooling, transformer tank design.

Text Books:

- 1. Electrical machine design by A. K. Sawhney, Dhanpatrai & Sons.
- **2.** Electrical System Design by M. K. Giridharan, I. K. International Publishing House Pvt. Ltd., 2011.
- **3.** Design of Electrical Machines by V. N. Mittle and A. Mittal, Standard Publishers Distributors, 4th Edition, 1998.

Reference Books:

- 1. Principles of Electrical machine design by M. G. Say & Parker Smith.
- 2. Electrical machine design by Balbir Singh by Khanna Publishers.

Course Title	Advanced Co	ontrol	Syste	ms (P	PE-I)	B. Tech. V	Sem			
Course Code	Category	Ho	urs/W	eek	Credits	5 Maximum Marks				
1802507	Professional Elective	L	Т	Р	С	Continuous Internal Assessment	End Exam	Total		
	(PEC)	3	1	0	3	30	70	100		
	Mid Exam Dura	tion: 2	2 Hrs			End Exam Duration : 3Hrs				
Course Obje analysis inclu	ectives: Student is ab ading controllability a	le to nd ob	learn servat	the St pility.	ate Space, l	Describing function, phase	plane and	stability		
Course Outo	comes: On successful	comp	letion	of thi	s course, the	e students will be able to				
CO 1	Understand the cond	cept o	f state	State	techniques					
CO 2	Analyse the stabili nonlinearities	ity of	linea	ır and	l nonlinear	Systems describing fund	ctions for c	lifferent		
CO 3	Construct the state model of linear time invariant systems and lyapunov functions for nonlinear systems									
CO 4	Determine Eigen va linear time invariant	llues s t syste	state tr ems	ansiti	on matrix e	xamine the controllability a	and observa	bility of		
CO 5	Design compensator	rs con	troller	s state	e feedback o	controller and observer				

<u>UNIT – I</u>

Linear System Design: Introduction of compensating networks – Lead, Lag, lead – lag cascade compensation in time domain –P, PI and PID controllers design using bode plot and root locus techniques.

<u>UNIT – II</u>

State variable descriptions: Concepts of state, state variables, state vector, state space model, representation in state variable form, phase variable representation – solution of state equations – state transition matrix.

$\underline{UNIT} - \underline{III}$

Controllability and Observability: Definition of controllability – controllability tests for continuous linear time invariant systems – Definition of observability – observability tests for continuous linear time invariant systems, diagonalization – canonical variable representation.

$\underline{UNIT} - IV$

Design of Control Systems: Introduction, Pole placement by state feedback, Full order and reduced order observers,

$\underline{UNIT} - \underline{V}$

Stability: Introduction, equilibrium points – stability concepts and definitions – stability in the sense of liapunov stability of linear system – methods of constructing liapunov functions for non – linear system – krasovskii's method – variable gradient method.

Text Books

- 1. Modern Control System Theory by M. Gopal, New Age International Publishers, 2nd edition, 1996.
- 2. Control System Engineering by I. J. Nagarath and M. Gopal, New Age International (P) Ltd.

Reference Books

- 1. Modern Control Engineering by K. Ogata, Prentice Hall of India, 3rd Edition, 1998.
- 2. Systems and Control by Stainslaw, H. Zak, Oxford Press, 2003.
- 3. Digital Control and State Variable Methods by M. Gopal, TMH, 1997.

Course Title	Instru	menta	tion (I	PE-I)	B. Tech. V Sem						
Course Code	Category	Hours/Week Credits				Maximum Marks					
1802508	Professional Elective Core	L	Т	Р	С	Continuous Internal Assessment	End Exam	Total			
	(PEC)	3	3	30	70	100					
	Mid Exam Dura	ation:		End Exam Duration : 3Hrs							
Course Objects classification data transmis meters, sever	ectives: The objective, , characteristics of si sion, telemetry, and c al types of transducer	e of th gnals, lata ac s and	their their quisiti	se is to represe on, wo se for t	o know erro entation, and orking princi measuremen	rs that occur in measure l signal modulation tecl ples of different signal a t of non-electrical quant	ement syster hniques, me analyzers an tities.	ms, their thods of d digital			
Course Outc	omes: On successful	comp	letion	of this	course, the s	students will be able to					
CO 1	Understand the type	es of e	rrors o	ccurrir	ng in measur	ement systems.					
CO 2	Differentiate types of data transmission and modulation technique										
CO 3	Apply digital techni	iques t	o meas	sure vo	oltage, freque	ency and speed.					
CO 4	Choose suitable trai	nsduce	rs for	measu	rement of no	n-electrical quantities.					

UNIT-I

Characteristics of Signals and their Representation: Measuring systems, performance characteristics, - static characteristics, dynamic characteristics; errors in measurement – gross errors, systematic errors, statistical analysis of random errors. signals and their representation: standard test, periodic, aperiodic, modulated signal, sampled data, pulse modulation and pulse code modulation.

<u>UNIT-II</u>

Data Transmission, Telemetry and DAS: Methods of data transmission – general telemetry system, frequency modulation (FM), pulse modulation (PM), pulse amplitude modulation (PAM), pulse code modulation (PCM) telemetry. Comparison of FM, PM, PAM & PCM. analog and digital data acquisition systems – components of analog DAS – types of multiplexing systems: time division and frequency division multiplexing – modern digital DAS– block diagram.

UNIT-III

Signal Analyzers, Digital Meters: Wave analysers- frequency selective analyzers, heterodyne, application of wave analyzers- harmonic analyzers, total harmonic distortion, spectrum analyzers, basic spectrum analyzers, spectral displays, vector impedance meter, q meter.

Peak reading and RMS voltmeters, digital voltmeters - successive approximation, ramp and integrating type-digital frequency meter-digital multimeter-digital tachometer.

UNIT-IV

Transducers: Definition of transducers, classification of transducers, advantages of electrical transducers, characteristics and choice of transducers; principle of operation of resistive, inductive, capacitive transducers, LVDT, strain gauge and its principle of operation, gauge factor, thermistors, thermocouples, synchros, piezoelectric transducers, photovoltaic, photoconductive cells, photo diodes.

UNIT-V

Measurement of Non-Electrical Quantities: Measurement of strain, gauge sensitivity, measurement of displacement, velocity, angular velocity, acceleration, force, torque, temperature, pressure, flow, liquid level.

Text Books

- 1. A course in Electrical and Electronic Measurements and Instrumentation, A.K. Sawhney, Dhanpat Rai & Co., 2012.
- 2. Transducers and Instrumentation, D.V.S Murty, Prentice Hall of India, 2nd Edition, 2004. **<u>Reference Books</u>**
- 1. Modern Electronic Instrumentation and Measurement technique, A.D Helfrick and W.D.Cooper, Pearson/Prentice Hall of India., 1990.
- 2. Electronic Instrumentation, H.S.Kalsi Tata MCGraw-Hill Edition, 2010.
- 3. Industrial Instrumentation Principles and Design, T. R. Padmanabhan, Springer, 3rd re print, 2009.

Course Title	Energy Convers	sion S	yster	ns (P	E – I)	B. Tech. V Sem						
Course Code	Category	Ηοι	ırs/W	eek	Credits	Maximum	um Marks End To					
1802509	Professional Elective (REC)	L	Т	Р	С	Continuous Internal Assessment	End Exam	Total				
	(PEC)	3	0	0	3	30	70	100				
	Mid Exam Duration	Hrs		End Exam Dura	ntion : 3Hrs							
Course Objective	ectives: The objectiv rgy production and im	re of	the of end	course ergy c	e is to lea conversion	rn about energy conversion systems on environment.	techniques,	sources of				
Course Outc	Course Outcomes: On successful completion of this course, the students will be able to											
CO 1	Understand the print storage.	ciples	and a	applic	ations of v	rarious non-conventional energ	gy systems a	nd energy				

CO 2	Analyze the properties and characteristics of wind, turbines and generators usedn in tidal power
CO 3	Analyze the solar cell operation and its test specifications
CO 4	Analyze the impact of energy conversion systems on environment and remedial measures.

<u>UNIT I</u>

Photo Voltaic Power Generation: Spectral distribution of energy in solar radiation, solar cell configurations, voltage developed by solar cell, photo current and load current, practical solar cell performance, test specifications for PV systems.

<u>UNIT II</u>

Wind Energy Conversion: Power from wind, properties of air and wind, types of wind Turbines, operating characteristics.

UNIT III

Tidal Power Station: Tides and tidal power stations, modes of operation, tidal project examples, turbines and generators for tidal power generation.

Ocean Energy Conversion: Types of ocean thermal energy conversion systems, Application of OTEC systems examples.

<u>UNIT IV</u>

Miscellaneous Energy Conversion Systems: biomass conversion, geothermal energy, thermo electric energy conversion, principles of EMF generation, description of fuel cells. Types of fuel cells, H_2 -O₂ Fuel cells, Application of fuel cells – Batteries, Description of batteries, Battery application for large power.

<u>UNIT V</u>

Environmental Effects: Environmental Effects of energy conversion systems, pollution from coal and preventive measures steam stations and pollution, acid rain, pollution free energy systems and nuclear power station pollution.

Text Books

- 1. "Energy conversion systems" by Rakosh das Begamudre, New age international Private Ltd., publishers, 1st Edition, 2000.
- 2. "Renewable Energy Resources" by John Twidell and Tony Weir, CRC Press (Taylor & Francis).

Course Title	Electrical I	Mach	ines -	IIL	ab	B. Tech. V Sem					
Course Code	Category	Hours/Week Cred		Credits	Maximum I	faximum Marks					
1802510	Professional Core	L	Т	Р	С	Continuous Internal Assessment	End Exam	Total			
	(PCC)	0	0	3	1.5	50	50 50 100				
						End Exam Dura	tion : 3Hrs				
Course Objection mot	ectives: The objections and synchronou	ive of s mac	f the hines	cours	se is to ar	alyze the performance of var	ious AC ma	chines like			
Course Outc	omes: On successfu	l com	pletic	on of	this course	, the students will be able to					
CO 1	Identify parts of tr	ansfo	rmers	and	AC machir	nes					
CO 2	Determine the peri	forma	nce o	f AC	machines						
CO 3	Choose the appara	tus in	expe	rimer	ntal circuit	based on loading and rating of	the AC mach	ines			

List of experiments

- 1. Brake test on Three Phase Induction Motor
- 2. No-load & Blocked rotor Tests on Three Phase Induction Motor
- 3. Speed Control of three phase Induction Motor
- 4. Equivalent Circuit of a Single Phase Induction Motor
- 5. Determination of X_d and X_q of a Salient Pole Synchronous Machine
- 6. Load test of a three phase alternator by Resistive, Inductive and Capacitive Loading
- Regulation of a Three –Phase Alternator by Synchronous Impedance & M.M.F. Methods.
- 8. Regulation of Three Phase Alternator by Z.P.F. Method.
- 9. V and Inverted V Curves of a 3 Phase Synchronous Motor.
- 10. Determination of transient, sub-transient and steady state reactance of an alternator.

Course Title	Control Systems &	Simu	latior	ı Lab)	B. Tec	h. V Sem		
Course Code	Category	Hou	ırs/W	/eek	Credits	Maximum Marks			
1802511	Professional Core (PCC)	L	Т	Р	С	Continuous Internal Assessment	End Exam	Total	
		3	3	30	70	100			
	Mid Exam Duration :		End Exam D	ouration :	3Hrs				
Course Ob controller, s state space a	jectives: The objective of the objectives and characteristics of analysis in MATLAB.	course servo	is to motc	learn or. Sta	the perfor ability anal	mance of second lysis in time and t	order syst frequency	tem, PID domain,	
Course Out	tcomes: On successful complet	ion of	this c	cours	e, the stude	ents will be able to)		
CO 1	Understand the performance voltage controlled DC motor	of sec	ond c	order	system, PII	D controller, sync	chros and	armature	
CO 2	Analyze the characteristics of	'magn	ietic a	mpli	fier and ser	vo motor			
CO 3	Evaluate stability of linear sy	stems	in tir	ie and	1 frequency	y domain using M	ATLAB		
CO 4	Convert transfer function to s	tate sp	bace a	nd vi	ce versa us	ing MATLAB			

List of the experiments (Any Ten - 8 from Conventional, 2 from MATLAB)

- 1. Time response of Second order system
- 2. Characteristics of Synchros
- 3. Programmable logic controller Study and verification of truth tables of logic gates, simple Boolean expressions and application of speed control of motor.
- 4. Effect of feedback on DC servo motor
- 5. Transfer function of DC Machine
- 6. Effect of P, PD, PI, PID Controller on a second order systems
- 7. Microprocessor based stepper motor controller
- 8. Temperature controller using PID
- 9. Characteristics of magnetic amplifiers
- 10. Characteristics of AC servo motor
- 11. Lag and lead compensator design in the frequency domain using MATLAB.
- 12. Linear system analysis (Time domain analysis) using MATLAB.
- 13. Stability analysis (Bode, Root Locus) of Linear Time Invariant system using MATLAB
- 14. State space model for classical transfer function using MATLAB Verification.

Course Title	Mini Project					B. Tech. V Sem		
Course Code	Category	Hours/Week			Credits	Maximum Marks		
1802513	PROJ	L	Т	Р	С	Continuous Internal Assessment	End Exams	Total
				-	2	100		100
Course Objective: The objective of the project is to enable the student to take up								
investigative study for social relevance.								
On successful completion of this course, the students will be able to								
CO 1	Understand core concepts and research findings relative to human development,							
	socialization, group dynamics and life course processes.							
CO 2	Identify and transfer existing ideas into new contexts and applications							
CO 3	Apply and transfer academic knowledge into the real-world.							
CO 4	Design a component or a product applying all the relevant standards and with realistic constraints							

The following are the rules and regulation for **Socially Relevant Projects**:

- 1. The student has to spend 50 to 60 Hrs in the semester on any project (Social Relevance) and submit a report for evaluation.
- 2. The project is evaluated for 100 marks in the semester by a committee consisting of head of the department, project mentor and one senior faculty member of the department.
- 3. A student shall acquire 2 credits assigned, when he/she secures 50% or more marks from the total of 100 marks.
- 4. In case, if a student fails, he/she shall resubmit the report.
- 5. There is no external evaluation for the socially relevant project.